Context-Dependent Effects in Guarded Interaction Trees

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Wednesday, May 7th 2025 @ ESOP'25 – Hamilton, Ontario, Canada



Context-Dependent Effects in Guarded Interaction Trees





Motivation

Denotational semantics and studying language interactions

Interaction Trees

Denotational semantics for first-order programs with first-order effects

Guarded Interaction Trees

Extends interaction trees to higher-order programs and effects

Context-Dependent Effects (This Work)

• Extends guarded interaction trees to context-dependent effects, e.g., (delimited) continuations, exceptions

Notivation

Denotational Semantics & Language Interaction

Studying Programs Formally

- Goal: study programming languages and their interactions formally
 - In a proof assistant like Rcoq (formerly Coq)
- We need to define programs' behavior (semantics)
 - Should capture the individual languages and their interaction
- Common choices:
 - Operational semantics
 - Denotational semantics

Operational Semantics

- Describe the mechanics of program execution
- Advantage
 - Simplicity: easy to understand and explain
 - Easily scales to sophisticated languages and features
- Disadvantage
 - we formalize



• Needs to be defined for each language (or combination/interaction there of)



Denotational Semantics

 Study those mathematical objects (also sound w.r.t. operational semantics)



Assign denotations (mathematical objects) to programs as their semantics



Denotational Semantics

 Study those mathematical objects (also sound w.r.t. operational semantics)

 Provides a rich common language (math) to combine programs and reason about language interactions



Assign denotations (mathematical objects) to programs as their semantics





Denotational Semantics

- Main challenge:
 - Coming up with a rich enough mathematical universe (domain)
 - Ordinary math (Rocq) is not sufficient
 - No non-termination
 - No side effects, *e.g.*, I/O, state
- Literature explores many solutions:
 - Scott domain theory, monads, etc.
 - **ITrees** are a recent proposal





7



Interaction Trees (ITrees)

Denotational Semantics for First-Order Languages



Main idea: construct a domain for

- Possibly non-terminating programs
- With side effects
- In the Rocq prover in which
 - All programs must terminate
 - There are no side effects
- Has since been used for several applications



Interaction Trees

Representing Recursive and Impure Programs in Coq

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Interaction trees (ITrees) are a general-purpose data structure for representing the behaviors of recursive programs that interact with their environments. A coinductive variant of "free monads," ITrees are built out of uninterpreted events and their continuations. They support compositional construction of interpreters from *event handlers*, which give meaning to events by defining their semantics as monadic actions. ITrees are expressive enough to represent impure and potentially nonterminating, mutually recursive computations, while admitting a rich equational theory of equivalence up to weak bisimulation. In contrast to other approaches such as relationally specified operational semantics, ITrees are executable via code extraction, making them suitable for debugging, testing, and implementing software artifacts that are amenable to formal verification

We have implemented ITrees and their associated theory as a Coq library, mechanizing classic domain- and category-theoretic results about program semantics, iteration, monadic structures, and equational reasoning. Although the internals of the library rely heavily on coinductive proofs, the interface hides these details so that clients can use and reason about ITrees without explicit use of Coq's coinduction tactics.

To showcase the utility of our theory, we prove the termination-sensitive correctness of a compiler from a simple imperative source language to an assembly-like target whose meanings are given in an ITree-based denotational semantics. Unlike previous results using operational techniques, our bisimulation proof follows straightforwardly by structural induction and elementary rewriting via an equational theory of combinators for control-flow graphs.

The original ITrees paper (POPL'20)





A monad defined as a co-inductive type in Rocq

CoInductive itree (E : Type -> Type) (R : Type) := Ret : R -> itree E R

- Constructors embed different kinds of computations:
 - Ret: the final value of the computation
 - Tau: delay (Tau c produces the same result as c delayed by a single step)
 - Vis: an effect with input type E A and output type A



Trees are First-Order

- ITrees can embed first-order imperative programs
- Xia et al. showed this for imp
 - Proved correctness of a compiler from imp to assembly
- ITrees do not support languages with higher-order (first class) functions, e.g., OCaml, Haskell
 - How do we translate λ 's?



```
(* Imp Syntax ------
Inductive expr : Set := ... (* omitted *)
Inductive imp : Set :=
 Assign (x : var) (e : expr)
 Seq (a b : imp)
 If (i : expr) (t e : imp)
 While (t : expr) (b : imp)
Skip.
(* Imp Events ------
Variant ImpState : Type \rightarrow Type :=
 GetVar (x : var) : ImpState value
 SetVar (x : var) (v : value) : ImpState unit.
```

Taken verbatim from the ITrees paper (Xia et al. 2020)



Trees are First-Order

- **Q**: How do we give a direct translation of λ 's?
- In higher-order languages λ 's are values, but do not fit in Ret
- Ideally, we add a new constructor to embed functions into the type it ree:

CoInductive itree (E : Type Ret : R -> itree E R Tau : itree E R -> itree Vis {A : Type } : E A ->

Trees are First-Order

- **Q**: How do we give a direct translation of λ 's?
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CoInductive itree (E : Type -> Type) (R : Type) := Ret : R -> itree E R Fun : (itree E R -> itree Tau : itree E R -> itree Vis {A : Type } : E A -> **Negative occurence**

- Not possible: the constructor Fun is not strictly positive (required by Rocq)
 - Guarded Interaction Trees (GITrees) solve this problem



Guarded Interaction Trees (GITrees)

Denotational Semantics for Higher-Order Languages



GITrees

- Main idea: Use guarded type theory
 - Lifts the strict positivity requirement
 - Uses Iris's guarded type theory
- Gave a program logic over GITrees
 - Using Iris's step-indexed program logic
- Studied language interactions
 - Safety of embedding linear types into an affine language



We present guarded interaction trees – a structure and a fully formalized framework for representing higherorder computations with higher-order effects in Coq, inspired by domain theory and the recently proposed interaction trees. We also present an accompanying separation logic for reasoning about guarded interaction trees. To demonstrate that guarded interaction trees provide a convenient domain for interpreting higher-order languages with effects, we define an interpretation of a PCF-like language with effects and show that this interpretation is sound and computationally adequate; we prove the latter using a logical relation defined using the separation logic. Guarded interaction trees also allow us to combine different effects and reason about them modularly. To illustrate this point, we give a modular proof of type soundness of cross-language interactions for safe interoperability of different higher-order languages with different effects. All results in the paper are formalized in Coq using the Iris logic over guarded type theory.

CCS Concepts: • Theory of computation \rightarrow Program semantics; Logic and verification; • Software and **its engineering** \rightarrow Software libraries and repositories.

Additional Key Words and Phrases: Coq, Iris, denotational semantics, logical relations

ACM Reference Format:

Interaction Trees

Dan Frumin, Amin Timany, and Lars Birkedal. 2024. Modular Denotational Semantics for Effects with Guarded Interaction Trees. Proc. ACM Program. Lang. 8, POPL, Article 12 (January 2024), 30 pages. https://doi.org/10. 1145/3632854

1 INTRODUCTION

Interaction trees [Xia et al. 2019] are a recently proposed formalism for representing and reasoning about (possibly) non-terminating programs with side effects in Coq (a terminating type theory without effects). Since its inception, interaction trees have been applied, including but not limited,

The original GITrees paper (POPL'23)



GITrees (Definition)

Guarded Type gitree (E : Effect) (R : Type) := Ret : R -> gitree E R

- Fun : ▶(gitree E R -> gitree E R) -> gitree E R Err : gitree E R
- Tau : ▶gitree E R -> gitree E R Vis (i : E) : (Ins i (▶gitree E R)) * (Outs i (▶gitree E R)) -> ▶gitree E R) -> gitree E R
- In the above the git ree arguments only appear guarded (*i.e.*, under $a \triangleright$)
- Fun: embeds function values
- Err: Indicates error, e.g., if a non-function value is applied to another value
- Input and output types can now also include ITrees (enables higher-order effects)

Note: very heavy use of syntactic sugar; Rocq does not directly support guarded types!



GITrees **Embedding** λ_{ref} : **STLC** with higher-order store

• A couple of examples:

Syntactic (STLC) λ $[[\lambda x \cdot e]]_{\rho} = Fut$

- Where
 - ρ maps free variables to gitree E R
 - next : $A \rightarrow \blacktriangleright A$

$$\operatorname{Meta-level}(\operatorname{Rocq})\lambda$$
$$\operatorname{n}\left(\operatorname{next}\left(\lambda v \cdot [[e]]_{\rho[x \mapsto v]}\right)\right)$$



GITrees **The Program Logic**

• A program logic (weakest precondition calculus)



- Intuitive reading:
 - The GITree α does not result in an Err, and
 - The result, a GITree value, *i.e.*, a Ret or Fun, satisfies P

GITrees The Program Logic – Effect Reification

- To define what GITrees "result in" we need to reify effects
 - We pick a **state** for each effect
 - For the heap of λ_{ref} we use finite partial maps $Loc \xrightarrow{fin} GITV$
 - An effect reifier maps a pair of input and state to an output and a state:



GITrees **The Program Logic**

- Provides basic reasoning principles for GITree operations, including effects • Which, based on their reification allow us to derive, e.g., wp-Load below:

Separation logic's points-to:	
the location ℓ stores value μ	$\ell \mapsto \mu$
	WP $\llbracket ! \ell \rrbracket_{\rho}$

$$\frac{\Phi(\mu)}{\{\nu \cdot \Phi(\nu)\}}$$
 WP-Load

GITrees **The Program Logic**

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Separation logic's points-to: $\mathcal{C} \mapsto \mu$ the location ℓ stores value μ WP $\llbracket ! \ell \rrbracket_{\rho}$

• Q: Modular reasoning? Ideally, from wp-load should be able to easily derivable:

$$WP \llbracket e \rrbracket_{\rho} \left\{ \nu . \exists \ell . \nu = Ret(\ell) \land WP \llbracket ! \ell \rrbracket_{\rho} \left\{ \mu . \Phi(\mu) \right\} \right\}$$

WP $[\![!e]\!]_{\rho} \{\nu \cdot \Phi(\nu)\}$

$$\frac{\Phi(\mu)}{\nu \cdot \Phi(\nu)} \quad \textbf{WP-Load}$$

WP-Load-Compound

GITrees The Program Logic – Modular Reasoning

• The wp-ноm rule, crucial for modular reasoning



- For any evaluation context K of λ_{ref} , $[[K]] \in Hom$
 - We can derive wp-Load-Compound from wp-Load and wp-Hom as! · is an evaluation context



Semantic criterion (Hom \subseteq GITree \rightarrow GITree); see Frumin et al. 2023

$$\frac{\alpha \left\{ \nu . WP f(\nu) \left\{ \mu . \Phi(\mu) \right\} \right\}}{f(\alpha) \left\{ \nu . \Phi(\nu) \right\}}$$
 WP-Hom

Context-Dependent Effects

Denotational Semantics for Control Effects

Control Effects

- Control effects' evaluation depends on and/or manipulates (part of) the valuation context, e.g., call/cc, shift-reset, exceptions
 - Operational semantics call/cc:
 - $K[\operatorname{call/cc}(x \cdot e)] \rightarrow K[e[\operatorname{cont} K/x]]$ $K[\text{throw } v \pmod{K'}] \rightarrow K'[v]$
- **Q**: Can we embed control effects in GITrees?

Can We Embed Control Effects in GITrees?

- The type of GITrees is rich enough to support control effects
- However, GITree reifiers are not suitable for control effects because
 - Reifiers do not have access to the continuations.

(Ins i (gitree E R) * State) -> option (Outs i (gitree E R) * State)

Can We Embed Control Effects in GITrees?

- The type of GITrees is rich enough to support control effects
- However, GITree reifiers are not suitable for control effects because
 - Reifiers do not have access to the continuations

• Solution: give the reifier access to the continuation of the effect

• This changes the program logic. It breaks wp-ноm!

(Ins i (gitree E R) * State) -> option (Outs i (gitree E R) * State)



Context-Dependent Reifiers Break WP-Hom

The wp-Hom rule is no longer valid (the result of α could depend on f)



- Inspired by previous work, we introduce context-local WP's (clwp)

$$f \in \text{Hom} \quad \text{CLWP } \alpha \ \left\{ \nu \ \cdot \right.$$
$$\text{CLWP } f(\alpha) \ \left\{ e^{-\frac{1}{2}} \right\} = 0 \ \text{CLWP} \left\{ e^{-\frac{$$

• Intuitively: clwp of α holds if wp holds and α has no context-dependent effect

 $\operatorname{CLWP} f(\nu) \left\{ \mu \cdot \Phi(\mu) \right\} \right\}$

• No clwp inference rule for context-dependent effects, e.g., $\|call/cc(x \cdot e)\|_{\rho}$



Denotational Semantics for Control Effects

- We give denotational semantics for
 - a language with call/cc
 - a language with shift-reset
- Show both soundness and adequacy wrt operational semantics See the exact statements

Soundness: $\Sigma_1 \to \Sigma_2 \implies \llbracket \Sigma_1 \rrbracket \cong \llbracket \Sigma_2 \rrbracket$ Adequacy : $\llbracket e \rrbracket \cong \llbracket n \rrbracket \implies e \to n$

 $\mathbf{E}[\![x]\!]_{\rho} = \rho(x)$ $\mathbf{E}[\![\mathsf{call/cc} (\mathsf{x}. e)]\!]_{\rho} = \mathrm{Callcc}(\lambda(f : \mathbf{\triangleright} \mathbf{IT} \to \mathbf{\triangleright} \mathbf{IT}). \mathbf{E}[\![e]\!]_{\rho[x \mapsto \mathsf{Fun}(\mathsf{next}(\lambda y. \mathsf{Tau}(f(\mathsf{next}(y)))))]})$ $\mathbf{E}[\![\mathsf{throw} \ e_1 \ \mathsf{to} \ e_2]\!]_{\rho} = \mathsf{get}_\mathsf{val}(\mathbf{E}[\![e_1]\!]_{\rho}, \lambda x. \, \mathsf{get}_\mathsf{fun}(\mathbf{E}[\![e_2]\!]_{\rho}, \lambda f. \, \mathsf{Throw}(x, f)))$ $\mathbf{V}[\![\mathsf{cont}\ K]\!]_{\rho} = \mathsf{Fun}(\mathsf{next}(\lambda x. \mathsf{Tau}(\mathbf{K}[\![K]\!]_{\rho}\ (\blacktriangleright \bullet)\ \mathsf{next}(x))))$ **K**[throw K to e]] $_{\rho} = \lambda x$. get val(**K**[[K]]] $_{\rho} x, \lambda y$. get fun(**E**[[e]]] $_{\rho}, \lambda f$. Throw(y, f))) $\mathbf{K}[\![\mathsf{throw} \ v \ \mathsf{to} \ K]\!]_{\rho} = \lambda x. \, \mathsf{get}_\mathsf{val}(\mathbf{V}[\![v]\!]_{\rho}, \lambda y. \, \mathsf{get} \quad \mathsf{fun}(\mathbf{K}[\![K]\!]_{\rho} \ x, \lambda f. \, \mathrm{Throw}(y, f)))$

An excerpt of the denotational semantics for call/cc

$$\begin{split} \mathbf{E}[\![\mathcal{D} \ \mathbf{e}]\!]_{\rho} &= \mathsf{Reset}(\mathbf{P}(\mathbf{E}[\![e]\!]_{\rho})) \\ \mathbf{E}[\![\mathcal{S} \times. e]\!]_{\rho} &= \mathsf{Shift}(\mathbf{P} \circ (\lambda \kappa. \mathbf{E}[\![e]\!]_{\rho,x \mapsto \mathsf{Fun}(\mathsf{next}(\lambda y. \mathsf{Tau}(\kappa(\mathsf{next}y))))})) \\ \mathbf{E}[\![e_1 \ @ \ e_2]\!]_{\rho} &= \mathsf{get_val}(\mathbf{E}[\![e_2]\!]_{\rho}, \lambda x. \mathsf{get_fun}(\mathbf{E}[\![e_1]\!]_{\rho}, \lambda y. \mathsf{Appcont}(\mathsf{next}(x), y)) \\ \mathbf{V}[\![\mathsf{cont} \ K]\!]_{\rho} &= \mathsf{Fun}(\mathsf{next}(\lambda x. \mathsf{Tick}(\mathbf{P}(\mathbf{K}[\![K]\!]_{\rho} x)))) \\ \mathbf{K}[\![K[\Box \ @ \ v]]\!]_{\rho} &= \lambda x. \mathbf{K}[\![K]\!]_{\rho}(\mathbf{E}[\![x \ @ \ v]\!]_{\rho}) \\ \mathbf{M}[\![mk]\!]_{\rho} &= \mathsf{map}(\lambda k. \mathbf{P} \circ \mathbf{K}[\![k]\!]_{\rho})\mathsf{mk} \\ \mathbf{S}[\![\langle e, \ K, \ mk\rangle_{\mathsf{eval}}]\!]_{\rho} &= (\mathbf{P}(\mathbf{E}[\![K[e]]\!]_{\rho}), \mathbf{M}[\![mk]\!]_{\rho}) \\ \mathbf{S}[\![\langle K, \ v, \ mk\rangle_{\mathsf{cont}}]\!]_{\rho} &= (\mathbf{P}(\mathbf{E}[\![K[v]]\!]_{\rho}), \mathbf{M}[\![mk]\!]_{\rho}) \\ \mathbf{S}[\![\langle mk, \ v\rangle_{\mathsf{mcont}}]\!]_{\rho} &= (\mathbf{P}(\mathbf{V}[\![v]\!]_{\rho}), \mathbf{M}[\![mk]\!]_{\rho}) \\ \mathbf{S}[\![\langle e\rangle_{\mathsf{term}}]\!]_{\rho} &= (\mathbf{P}(\mathbf{E}[\![e]\!]_{\rho}), []) \\ \mathbf{S}[\![\langle v\rangle_{\mathsf{ret}}]\!]_{\rho} &= (\mathbf{V}[\![v]\!]_{\rho}, []) \end{split}$$

An excerpt of the denotational semantics for shift-reset

in the paper!





Denotational Semantics for Control Effects

See the exact statements in the paper!

- Soundness: $\Sigma_1 \to \Sigma_2 \implies [\![\Sigma_1]\!] \cong [\![\Sigma_2]\!]$ Adequacy : $\llbracket e \rrbracket \cong \llbracket n \rrbracket \implies e \to * n$
- Adequacy is proven
 - Using bi-orthogonal logical relation
 - A well-known technique
 - Expressed in terms of wp's (not
 - Bi-orthogonal LR "bake in" mode w.r.t. evaluation contexts

$\mathbf{E}[\![x]\!]_{\rho} = \rho(x)$ $\mathbf{E}[\![\mathsf{call/cc} (\mathsf{x}. e)]\!]_{\rho} = \mathrm{Callcc}(\lambda(f : \mathbf{\triangleright} \mathbf{IT} \to \mathbf{\triangleright} \mathbf{IT}). \mathbf{E}[\![e]\!]_{\rho[x \mapsto \mathsf{Fun}(\mathsf{next}(\lambda y. \mathsf{Tau}(f(\mathsf{next}(y)))))]})$ $\mathbf{E}[\![\mathsf{throw} \ e_1 \ \mathsf{to} \ e_2]\!]_{\rho} = \mathsf{get}_\mathsf{val}(\mathbf{E}[\![e_1]\!]_{\rho}, \lambda x. \, \mathsf{get}_\mathsf{fun}(\mathbf{E}[\![e_2]\!]_{\rho}, \lambda f. \, \mathsf{Throw}(x, f)))$ $\mathbf{V}[\![\operatorname{cont} K]\!]_{\rho} = \operatorname{Fun}(\operatorname{next}(\lambda x. \operatorname{Tau}(\mathbf{K}[\![K]\!]_{\rho} (\blacktriangleright \bullet) \operatorname{next}(x))))$ $\mathbf{K}[[\mathsf{throw} \ K \ \mathsf{to} \ e]]_{\rho} = \lambda x. \, \mathsf{get}_\mathsf{val}(\mathbf{K}[[K]]_{\rho} \ x, \lambda y. \, \mathsf{get}_\mathsf{fun}(\mathbf{E}[[e]]_{\rho}, \lambda f. \, \mathrm{Throw}(y, f)))$ $\mathbf{K}[\![\mathsf{throw} \ v \ \mathsf{to} \ K]\!]_{\rho} = \lambda x. \, \mathsf{get}_\mathsf{val}(\mathbf{V}[\![v]\!]_{\rho}, \lambda y. \, \mathsf{get} \quad \mathsf{fun}(\mathbf{K}[\![K]\!]_{\rho} \ x, \lambda f. \, \mathsf{Throw}(y, f)))$

An excerpt of the denotational semantics for call/cc

$$\begin{array}{l} \textbf{LR} \\ \textbf{F} \left[\mathbb{D} \ \textbf{e} \right]_{\rho} = \textbf{Reset}(\textbf{P}(\textbf{E}[e]]_{\rho})) \\ \textbf{E} \left[\mathbb{S} \ \textbf{x}. \ e \right]_{\rho} = \textbf{Shift}(\textbf{P} \circ (\lambda \kappa. \textbf{E}[e]]_{\rho, x \mapsto \textbf{Fun}(\texttt{next}(\lambda y. \texttt{Tau}(\kappa(\texttt{next}y))))})) \\ \textbf{E} \left[\mathbb{E} 1 \ \textbf{Q} \ e_{2} \right]_{\rho} = \textbf{get}_\texttt{val}(\textbf{E}[e_{2}]]_{\rho}, \lambda x. \textbf{get}_\texttt{fun}(\textbf{E}[e_{1}]]_{\rho}, \lambda y. \textbf{Appcont}(\texttt{next}(x), y)) \\ \textbf{E} \left[e_{1} \ \textbf{Q} \ e_{2} \right]_{\rho} = \textbf{get}_\texttt{val}(\textbf{E}[e_{2}]]_{\rho}, \lambda x. \textbf{get}_\texttt{fun}(\textbf{E}[e_{1}]]_{\rho}, \lambda y. \textbf{Appcont}(\texttt{next}(x), y)) \\ \textbf{V} \left[\textbf{Cont} \ \textbf{K} \right]_{\rho} = \textbf{get}_\texttt{val}(\textbf{E}[e_{2}]]_{\rho}, \lambda x. \textbf{get}_\texttt{fun}(\texttt{next}(\lambda y. \texttt{Tau}(\kappa(\texttt{next}y))))) \\ \textbf{V} \left[\textbf{Cont} \ \textbf{K} \right]_{\rho} = \textbf{get}_\texttt{val}(\textbf{E}[e_{2}]]_{\rho}, \lambda x. \textbf{get}_\texttt{fun}(\texttt{next}(\lambda y. \texttt{Tau}(\kappa(\texttt{next}y))))) \\ \textbf{K} \left[\textbf{K} \left[\textbf{Q} \ e_{2} \right] \right]_{\rho} = \textbf{get}_\texttt{val}(\textbf{E}[e_{2}]]_{\rho}, \lambda x. \textbf{get}_\texttt{fun}(\texttt{next}(\lambda y. \texttt{Tau}(\kappa(\texttt{next}y))))) \\ \textbf{K} \left[\textbf{K} \left[\textbf{Q} \ e_{2} \right] \right]_{\rho} = \textbf{Fun}(\texttt{next}(\lambda x. \texttt{Tick}(\textbf{P}(\textbf{K}[M]]_{\rho}, \textbf{M}))) \\ \textbf{K} \left[\textbf{K} \left[\textbf{M} \right] \right]_{\rho} = \textbf{Fun}(\texttt{next}(\lambda x. \texttt{Tick}(\textbf{P}(\textbf{K}[M]]_{\rho}), \textbf{M}[mk]]_{\rho}) \\ \textbf{M} \left[mk \right]_{\rho} = \texttt{map}(\lambda k. \textbf{P} \circ \textbf{K} \left[k \right] \right]_{\rho}) \textbf{M} \left[mk \right]_{\rho} \\ \textbf{S} \left[\langle e, \ K, \ mk \rangle_{eval} \right] \right]_{\rho} = (\textbf{P}(\textbf{E} \left[\textbf{K}[e] \right]_{\rho}), \textbf{M} \left[mk \right] \right]_{\rho}) \\ \textbf{S} \left[\langle k, \ v, \ mk \rangle_{cont} \right] \right]_{\rho} = (\textbf{P}(\textbf{E} \left[\textbf{K}[v] \right] \right]_{\rho}), \textbf{M} \left[mk \right] \right]_{\rho} \\ \textbf{S} \left[\langle e_{k}, \ v, \ mk \rangle_{cont} \right] \right]_{\rho} = (\textbf{P}(\textbf{E} \left[\textbf{K}[v] \right]_{\rho}), \textbf{M} \left[mk \right] \right]_{\rho}) \\ \textbf{S} \left[\langle e_{k} \ e_{m} \right] \right]_{\rho} = (\textbf{P}(\textbf{E} \left[e_{1} \right]_{\rho}), \textbf{M} \left[mk \right] \right]_{\rho}) \\ \textbf{S} \left[\langle e_{k} \ e_{m} \right] \right]_{\rho} = (\textbf{P}(\textbf{E} \left[e_{1} \right]_{\rho}), \textbf{M} \left[mk \right] \right]_{\rho}) \\ \textbf{S} \left[\langle e_{k} \ e_{m} \right] \right]_{\rho} = (\textbf{V} \left[v \right] \right]_{\rho}, \textbf{M} \left[mk \right] \right]_{\rho}) \\ \textbf{S} \left[\langle v \ e_{m} \right] \right]_{\rho} = (\textbf{V} \left[v \ e_{m} \right]_{\rho}) \\ \textbf{S} \left[\langle v \ e_{m} \right] \right]_{\rho} = (\textbf{V} \left[v \ e_{m} \right]_{\rho}) \\ \textbf{S} \left[\langle e_{k} \ e_{m} \right] \right]_{\rho} = (\textbf{V} \left[v \ e_{m} \right]_{\rho}) \\ \textbf{S} \left[\langle e_{k} \ e_{m} \right] \right]_{\rho} = (\textbf{V} \left[v \ e_{m} \right]_{\rho}) \\ \textbf{S} \left[\langle e_{k} \ e_{m} \right] \right]_{\rho} = (\textbf{V} \left[v \ e_{m} \right]_{\rho}) \\ \textbf{S} \left[\langle e_{k} \ e_{m} \right] \right]_{\rho}$$

An excerpt of the denotational semantics for shift-reset





Language Interaction

- We show semantic type safety for λ_{embed}
 - Only allow embedding pure programs of λ_{delim}
- *Bi-orthogonal* LR for λ_{delim} using wp's
- Non-bi-orthogonal LR for λ_{embed} using clwp's
 - Key point: we can use clwp's for all of λ_{embed}
 - **Derive** clwp for embed *e* from a wp for *e*:
 - The wp comes from the bi-orthogonal LR



λ_{delim} : A language with shift-reset

types

$$Ty \ni \tau \quad ::= \mathbb{N} | \mathbf{1} | \tau \to \sigma | \operatorname{ref}(\tau)$$
expressions $Expr \ni e \quad ::= x | () | e_1 e_2 | e_1 \oplus e_2 | n | \lambda x. e_1 | \ell | \operatorname{ref}(e) | !e | e_1 \leftarrow e_2 | embended
$$\emptyset \vdash_{pure} e : \mathbb{N}$$

$$\overline{\Gamma} \vdash_{embed} e : \mathbb{N}$$$

 λ_{embed} : A language with no control effects where we embed pure (properly delimited) expressions from λ_{delim}



