Priority Queues

- MakeQueue
- Insert(Q,k,p)
- Delete(Q,k)
- DeleteMin(Q)
- Meld(Q_1, Q_2)
- Empty(Q)
- Size(Q)
- FindMin(Q)

create new empty queue

insert key k with priority p

delete key *k* (given a pointer)

delete key with min priority

merge two sets

returns if empty

returns #keys

returns key with min priority

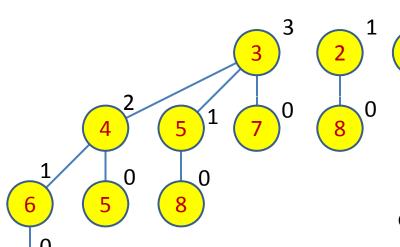
Priority Queues – Ideal Times

MakeQueue, Meld, Insert, Empty, Size, FindMin: O(1)Delete, DeleteMin: $O(\log n)$

Thm

¹⁾ Meld $O(n^{1-\epsilon}) \implies$ DeleteMin $\Omega(\log n)$ ²⁾ Insert, Delete $O(t) \implies$ FindMin $\Omega(n/2^{O(t)})$

- 1) Follows from $\Omega(n \cdot \log n)$ sorting lower bound
- 2) [G.S. Brodal, S. Chaudhuri, J. Radhakrishnan, *The Randomized Complexity of Maintaining the Minimum*. In Proc. 5th Scandinavian Workshop on Algorithm Theory, volume 1097 of Lecture Notes in Computer Science, pages 4-15. Springer Verlag, Berlin, 1996]



Binomial Queues

[Jean Vuillemin, *A data structure for manipulating priority queues,* Communications of the ACM archive, Volume 21(4), 309-315, 1978]

Binomial tree

- each node stores a (k,p) and satisfies heap order with respect to priorities
- all nodes have a rank r (leaf = rank 0, a rank r node has exactly one child of each of the ranks 0..r-1)

Binomial queue

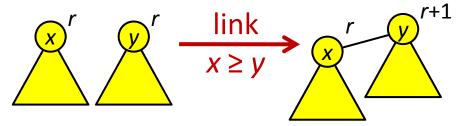
 forest of binomial trees with roots stored in a list with strictly increasing root ranks

Problem

Implement binomial queue operations to achieve the ideal times in the **amortized** sense

Hints

1) Two rank *i* trees can be linked to create a rank *i*+1 tree in *O*(1) time



2) Potential $\Phi = \max \operatorname{rank} + \#\operatorname{roots}$

Dijkstra's Algorithm

(Single source shortest path problem)

```
Algorithm Dijkstra(V, E, w, s)
  Q := MakeQueue
  dist[s] := 0
  Insert(Q, s, 0)
  for v \in V \setminus \{s\} do
     dist[v] := +\infty
     Insert(Q, v, +\infty)
  while Q \neq \emptyset do
     v := DeleteMin(Q)
     foreach u:(v,u)\in E do
         if u \in Q and dist[v]+w(v, u) < dist[u] then
            dist[u] := dist[v] + w(v, u)
            DecreaseKey(u, dist[u])
```

```
n \times lnsert + n \times DeleteMin + m \times DecreaseKey
Binary heaps / Binomial queues : O((n + m) \cdot log n)
```

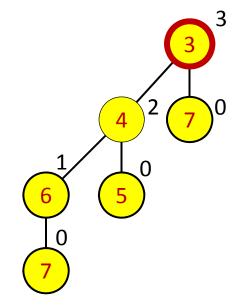
Priority Bounds

	Binomial Queues [Vuillemin 78]	Fibonacci Heaps [Fredman, Tarjan 84]			Run-Relaxed Heaps [Driscoll, Gabow, Shrairman, Tarjan 88]	[Brodal 96]
Insert	1		1		1	1
Meld	1		1		-	1
Delete	log n		log n		log n	log n
DeleteMin	log n		log n		log n	log n
DecreaseKey	log n		1		1	1
Amortized Worst-case						

Dijkstra's Algorithm $O(m + n \cdot \log n)$ (and Minimum Spanning Tree $O(m \cdot \log^* n)$)

Fibonacci Heaps

[Fredman, Tarjan, Fibonacci Heaps and Their Use in Improved Network Algorithms, Journal of the ACM, Volume 34(3), 596-615, 1987]



F-tree

- heap order with respect to priorities
- all nodes have a rank $r \in \{\text{degree}, \text{degree} + 1\}$ ($r = \text{degree} + 1 \Leftrightarrow \text{node is marked}$ as having lost a child)
- The i'th child of a node from the right has rank ≥ i 1
- Fibonacci Heap
 - forest (list) of F-trees (trees can have equal rank)

Fibonnaci Heap Property

Thm Max rank of a node in an F-tree is O(log n)

Proof A rank r node has at least 2 children of rank $\geq r - 3$. By induction subtree size is at least $2^{Lr/3J}$

(in fact the size is at least φ^r , where $\varphi=(1+\sqrt{5})/2$)

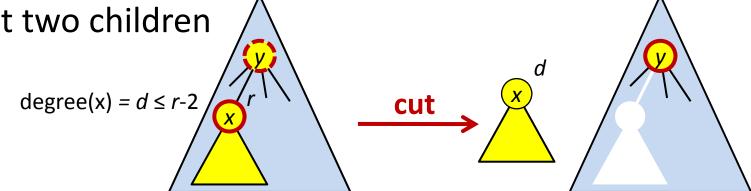
Problem

Implement Fibonacci Heap operations with amortized O(1) time for all operations, except $O(\log n)$ for deletions

Hints

1) Two rank *i* trees can be linked to create a rank i+1 tree in O(1) time x^r y^r y^r





3) Potential $\Phi = 2 \cdot \text{marks} + \text{\#roots}$

Implemenation of Fibonacci Heap Operations

FindMin Maintain pointer to min root

Insert Create new tree = new rank 0 node +1

Join Concatenate two forests unchanged

Delete DecreaseKey -∞ + DeleteMin

DeleteMin Remove min root ⁻¹

+ add children to forest $+O(\log n)$

+ bucketsort roots by rank only O(log n) not linked below

+ link while two roots equal rank -1 each

DecreaseKey Update priority + cut edge to parent +3

+ if parent now has r - 2 children,

recursively cut parent edges -1 each, +1 final cut

* = potential change

Worst-Case Operations

(without Join)

[Driscoll, Gabow, Shrairman, Tarjan, Relaxed Heaps: An Alternative to Fibonacci Heaps with Applications to Parallel Computation, Communications of the ACM, Volume 34(3), 596-615, 1987]

Basic ideas

- Require ≤ max-rank + 1 trees in forest (otherwise ∃rank r where two trees can be linked)
- Replace cutting in F-trees by having O(log n) nodes violating heap order
- Transformation replacing two rank r violations by one rank r+1 violation